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# Geometry Scaling of Microwave Filters Using an Adaptive Homotopy Continuation Method


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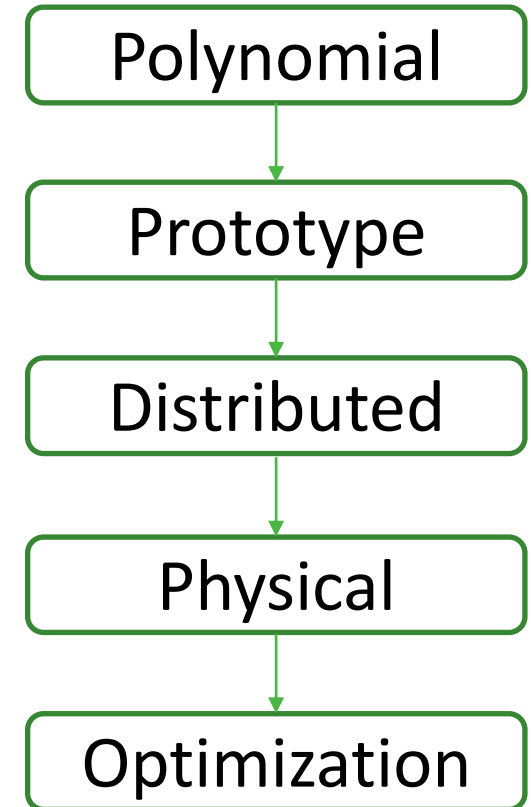
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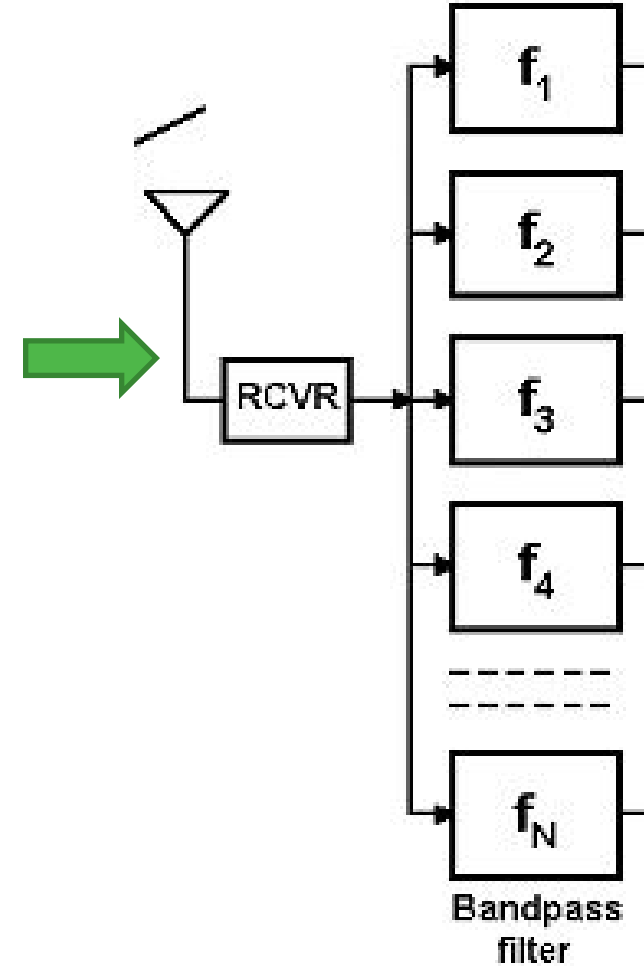
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- **Background**
- **Geometry scaling of Microwave Filters Using an Adaptive Homotopy Continuation Method**
  - Adaptive Homotopy Continuation Method
  - Inverse Model Construction
- **Experiment Results and Comparisons**
- **Conclusion**


- **Microwave Filters**
  - Components for passing and attenuating signals at specific frequency ranges
- **The Filter Design Process** 
  - Follow several steps at different levels
  - The optimization is commonly based on full-wave electromagnetic (EM) simulation
    - Accounts for **90% of** the total design time

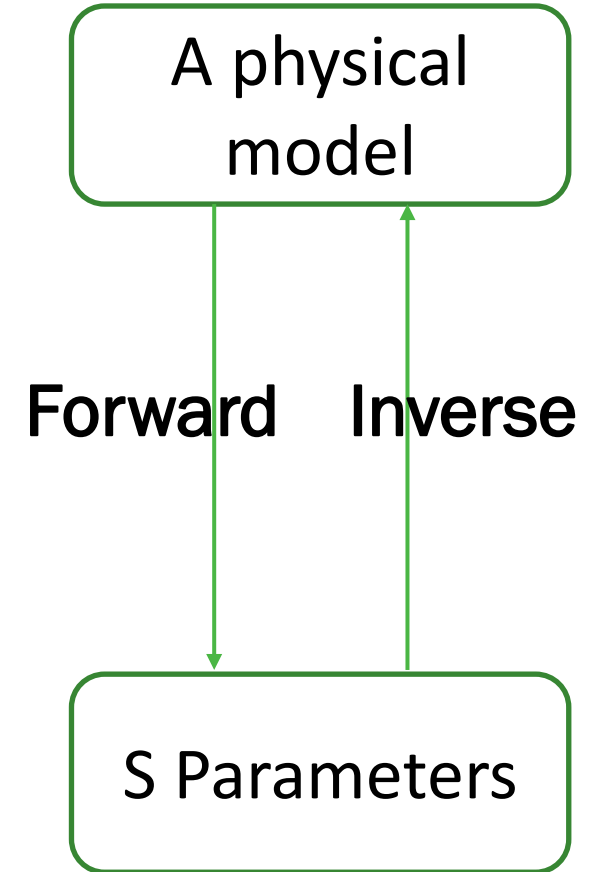


- Geometry Scaling
  - To redesign filters with the same structure for different required center frequencies and bandwidths
  - E.g., a multiplexing network with multiple channels
- Human effort
  - The synthesis technique for a single filter is well-established
  - “trial and error” to improve efficiency by skipping steps

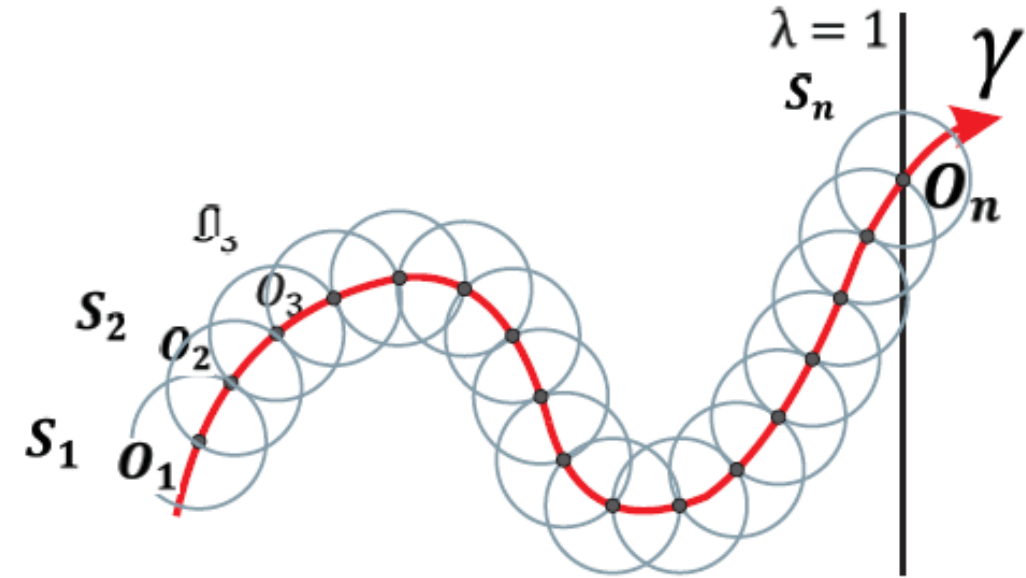


- **Challenges:**
  - Too much human participation
  - Non-linearity can result in failure
  - Low efficiency
  - Can not be reused
- **Inverse model** can be a promising solution

- Inverse model 
  - Output the physical parameters given the electrical parameters
- Why is the inverse model promising?
  - Be reused to directly give the filter's dimension without repetitive EM simulations
- How to train a reliable inverse model?
  - A high-quality database is needed
  - **Homotopy Continuation (HC)** can be applied



- Homotopy Continuation (HC)
  - Divide a problem into a series of intermediate sub-problems
  - Each sub-problem is solved from its previous solution
    - A predictor followed by a corrector
- Why is HC applied?
  - More linear and easier to solve
  - The database is built by collecting all the intermediate solutions



An example of HC applications  
[1]

- **1. HC Step Considerations**

- Too large: fail to solve the next sub-problem
- Too small: the computational cost increases

- **Adaptive HC steps  $\delta^i$**

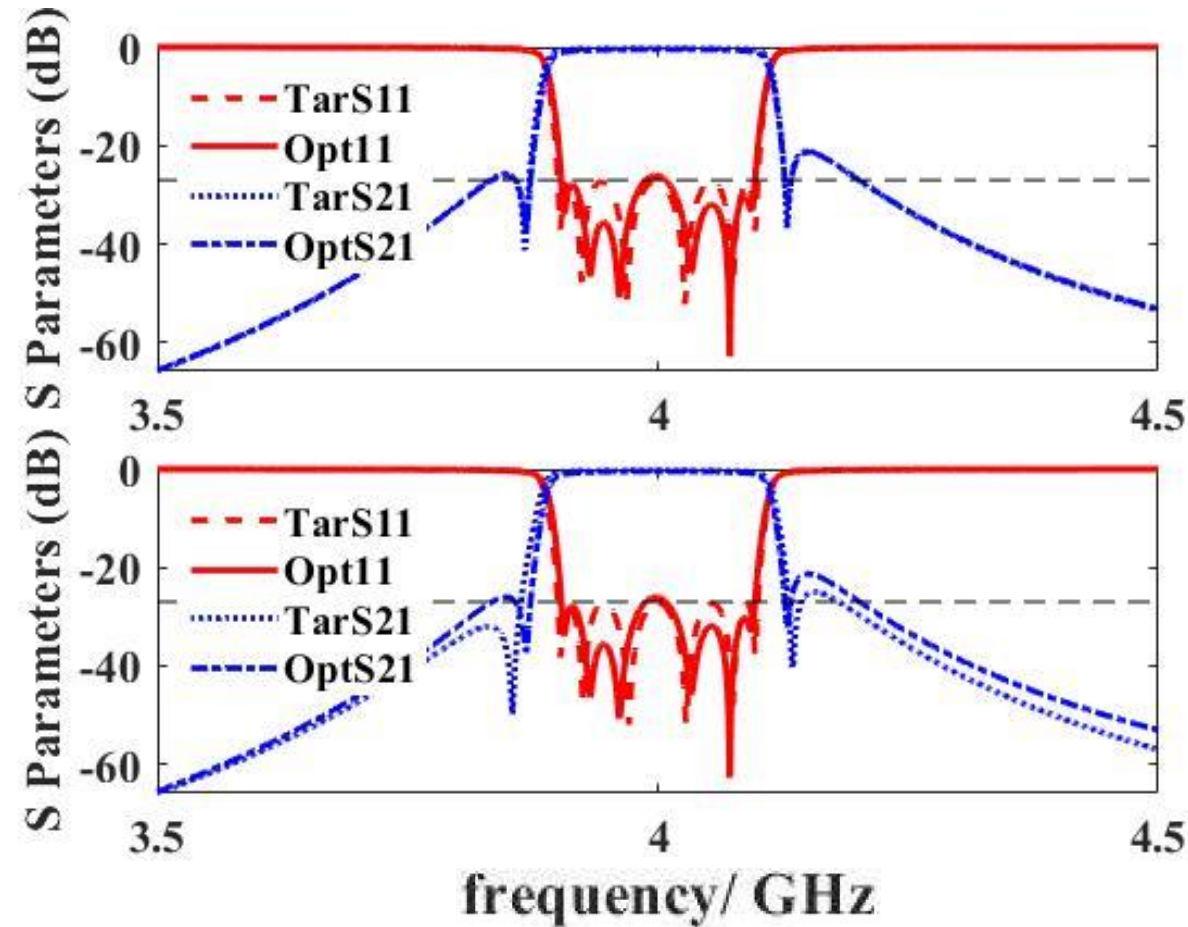
- Adjusted by the responses of physical parameters from the predictor

$$\begin{aligned}\delta^i &= 2 * \delta^{i-1}, \text{ if } C^{i-1} < \varepsilon \\ \delta^i &= 0.5 * (\delta^{i-1} + \delta^{i-2}), \text{ if } C^{i-1} \geq \varepsilon \ \& \ C^{i-2} < \varepsilon \\ \delta^i &= \delta^{i-1}, \text{ if } C^{i-1} \geq \varepsilon \ \& \ C^{i-2} > \varepsilon\end{aligned}$$

- $BW^{i-1} = \text{Predictor}(x)$  is solved as  $x = L^{i-1}$ , then  $BW^i = BW^{i-1} + \delta^i$
- $C^{i-1}$  is the cost function of  $\text{Predictor}(L^{i-1})$

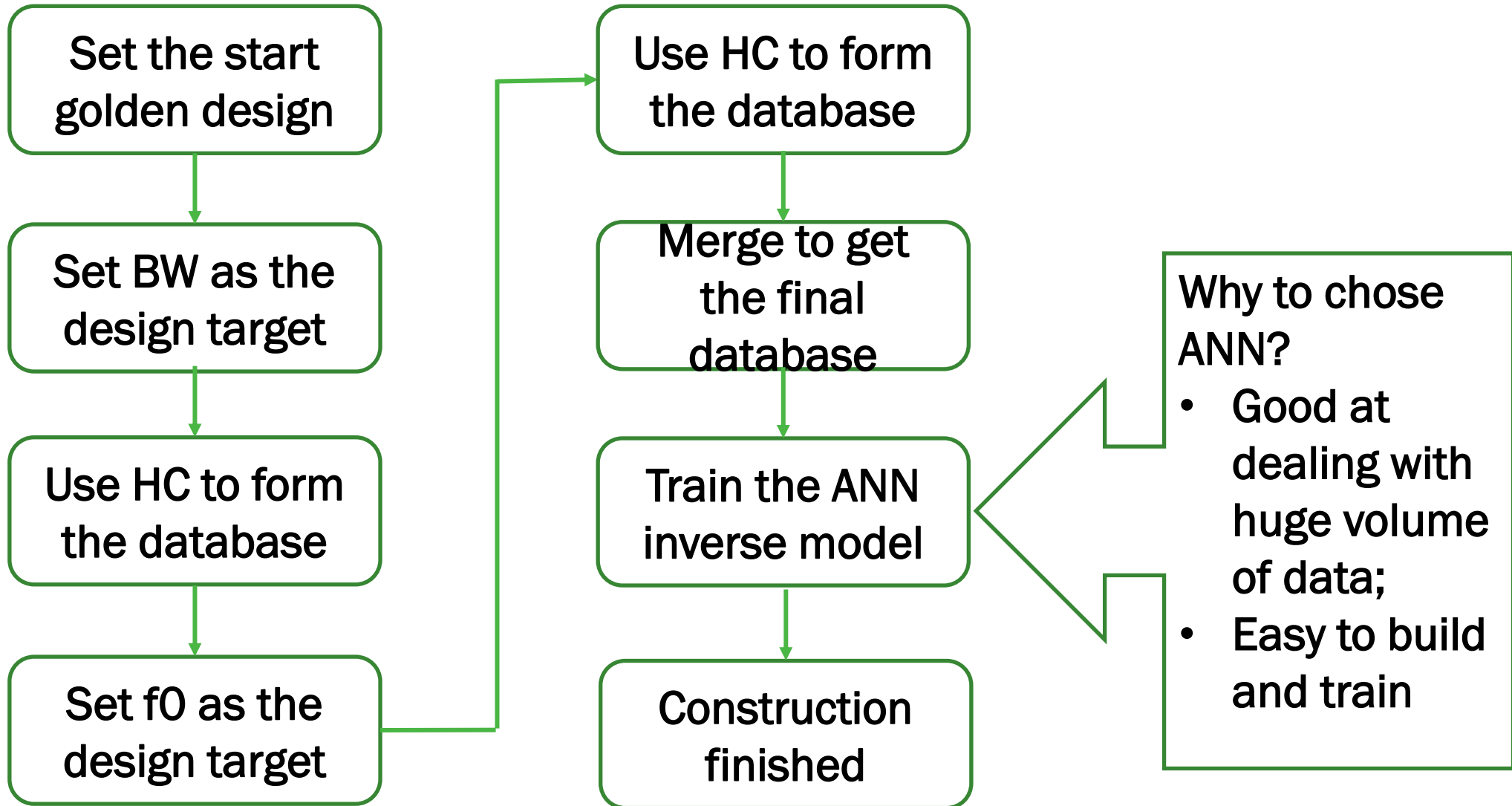


- **2. Inclusion of Transmission Zeros (TZs)**
  - For the precise control of the response shape
  - Top figure: consider the shift of TZs
  - Bottom figure: the target normal TZS are the same as the golden design

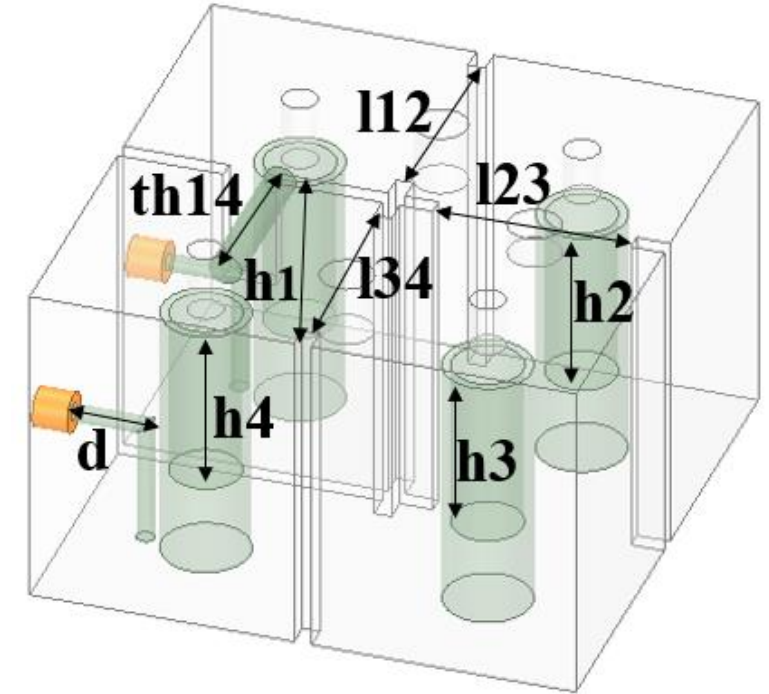


Comparisons between target and optimal responses

# Inverse Model Construction



- Set up
  - A fourth-order coaxial resonator filter
  - 9 physical parameters
  - 2 TZs
  - Golden design at  $BW = 3\%$ ,  $f_0 = 1.95$  GHz



Desired BW  
and  $f_0$

The well trained  
ANN

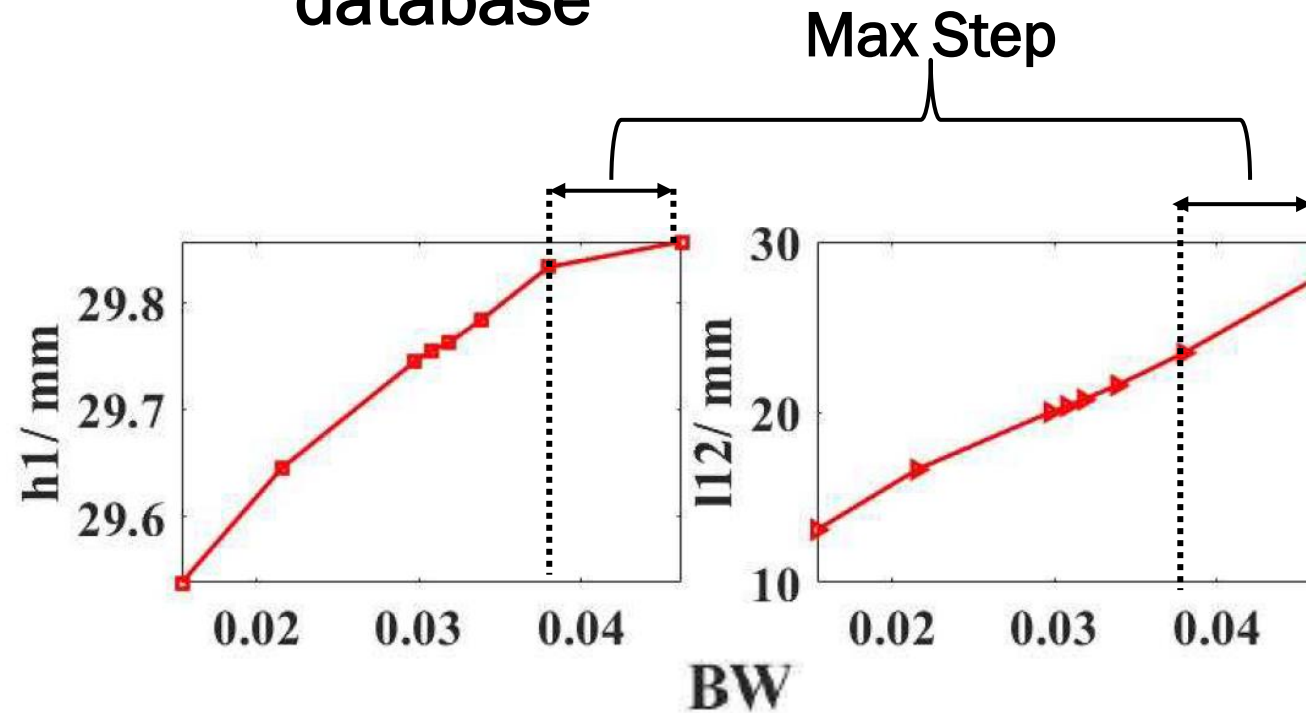
Target TZs

Physical  
parameters

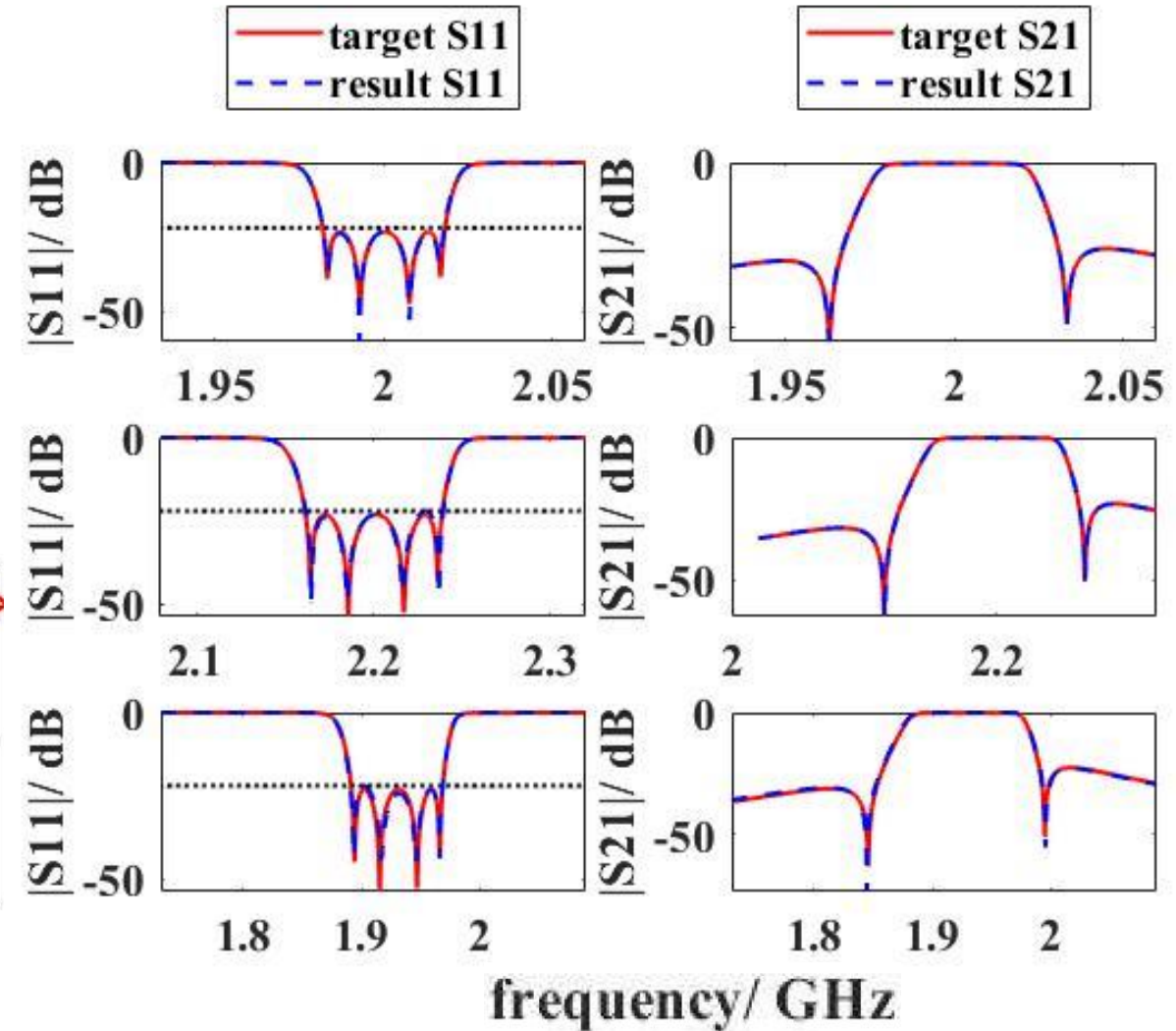
Tune if  
necessary

## Results

- An  $8 \times 7$  grid is formed as the database



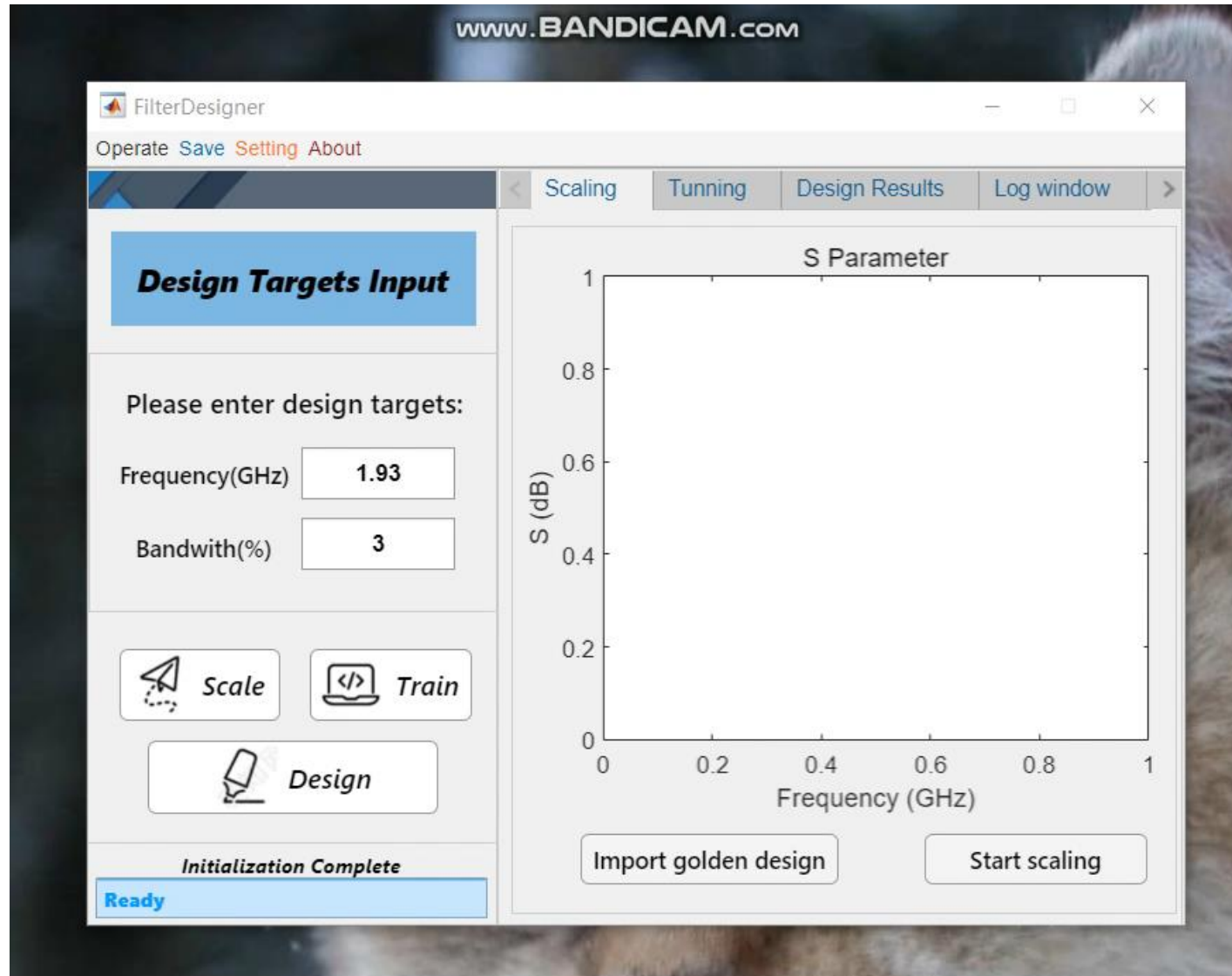
Some design variables vary with BW



Three examples of geometry scaling



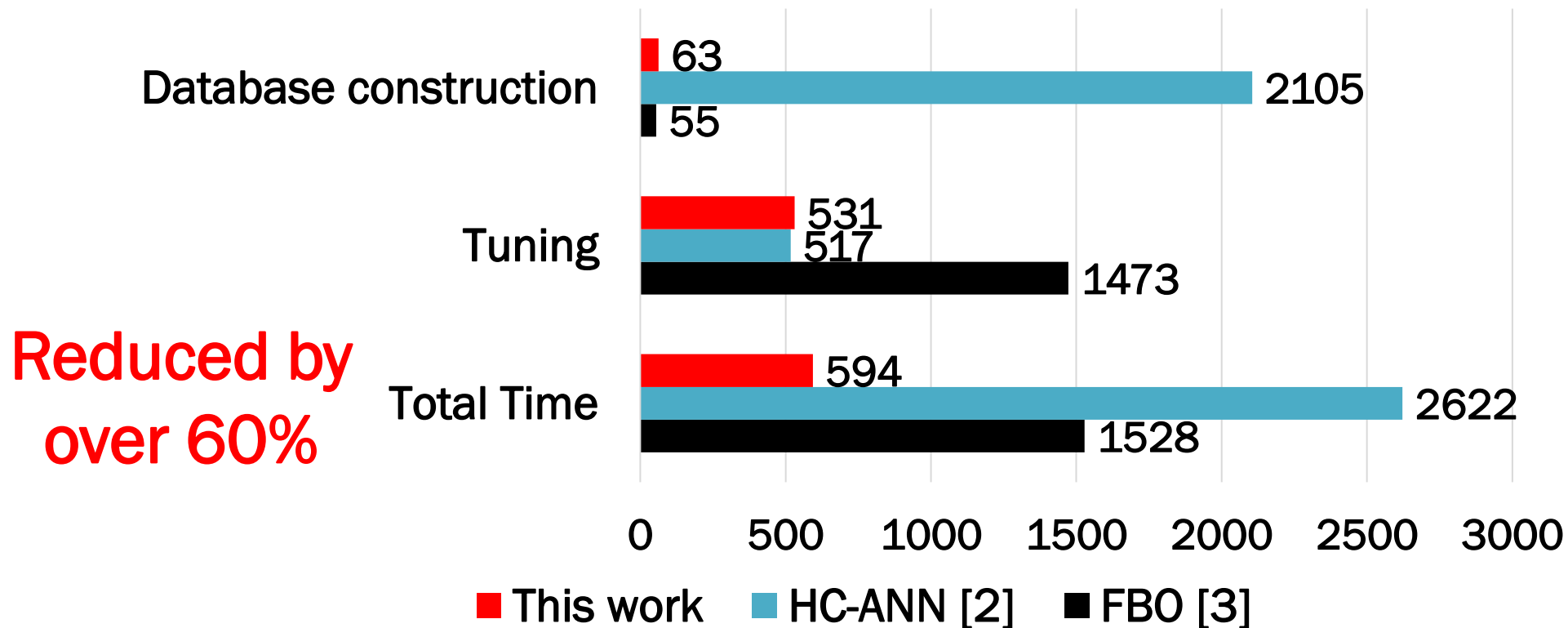
# Experiment Results



# Comparisons

- [2]: small steps; more cost on the database construction
- [3]: large steps; more cost on  tunings

Comparisons of the required time (Unit: min)



# Conclusions

- To perform geometry scaling for multiple desired design specifications **automatically and efficiently** can be challenging
- Adaptive steps are embedded into HC
- TZs are included in the database
- To **generalize** this work to other types of filters and other design specifications besides the bandwidth and center frequency

- [1] G. Diaz-Arango, L. Hernandez-Martinez, A. Sarmiento-Reyes and H. Vazquez-Leal, “Fast and robust homotopy path planning method for mobile robotics,” *2016 IEEE Intern. Symposium On Circuits and Systems (ISCAS)*, Montreal, QC, Canada, 22-25 May. 2016.
- [2] C. Roy and K. Wu, “Homotopy optimization and ANN modeling of millimeter-wave SIW cruciform coupler,” *IEEE. Trans. Microw. Theory Techn.*, vol. 70, no. 11, pp. 4751–4764, Nov. 2022.
- [3] S. Koziel and J.W.Bandler, “Low-cost dimension scaling and tuning of microwave filters using response features,” *2016 IEEE MTT-S International Microwave Symposium (IMS)*, San Francisco, CA, USA, 22-27 May. 2016.