





WE1G-5



A Next-Generation Hybrid Analog Beamsteering and MIMO Digital Radar for Highly Automated Driving

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Outline



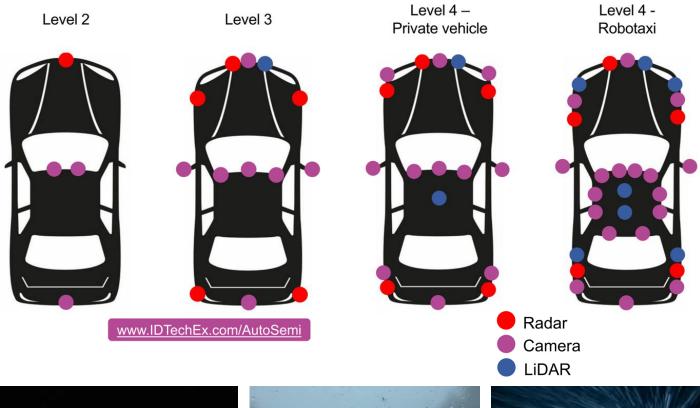
- Motivation and introduction of a long-range hybrid (beamsteering + MIMO) imaging radar
- Metawave Carson radar design and implementation
 - Beamformer TX/RX IC
 - Antenna-in-Package
 - System design, implementation, and RF performance
- Radar demo video
- Conclusions





Introduction





- Sensor suite evolution for L2 – L5 driving: more features and increased demand for robustness requires more sensors.
- Radar is a core sensor to cope with challenging weather conditions.





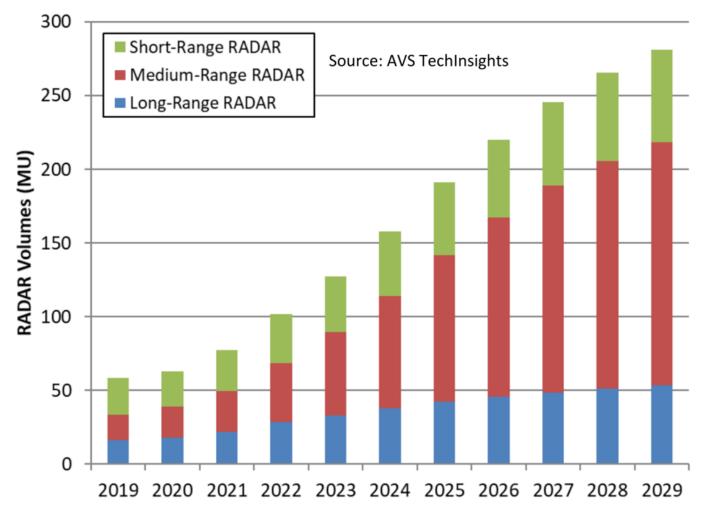




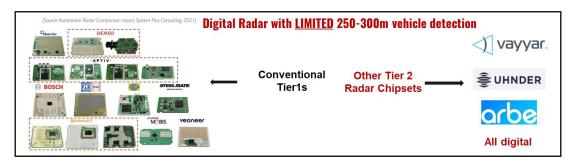


Introduction





- Strong growth forecast for automotive radar
- Accelerated adoption of 4D imaging radar: distance + direction + velocity + elevation

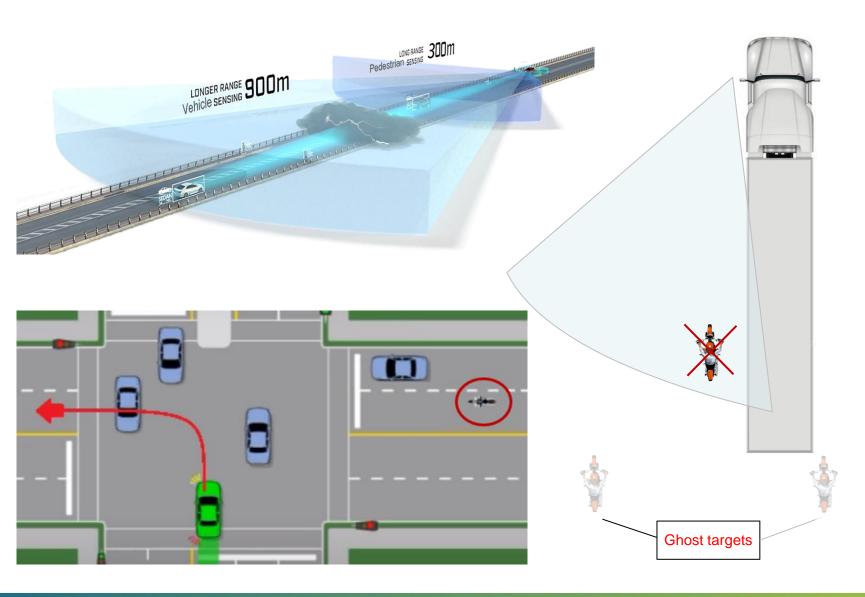






Introduction





Technical Challenges for MIMO-based radars:

- Long range detection (e.g., 900m for car, 300m for pedestrian)
- Corner radar detecting motorcycle at 250m
- Truck rear-view longrange detection, e.g., mitigate multipath effects & eliminate ghost targets



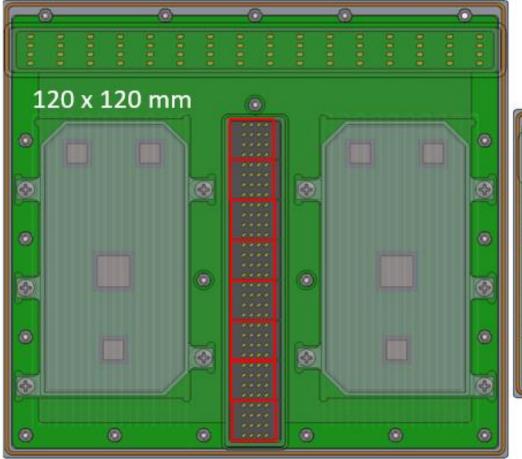


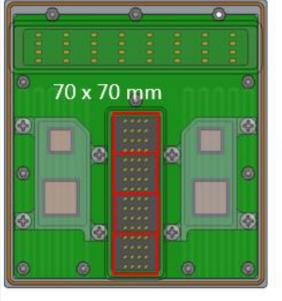
Carson Imaging Radar Hardware

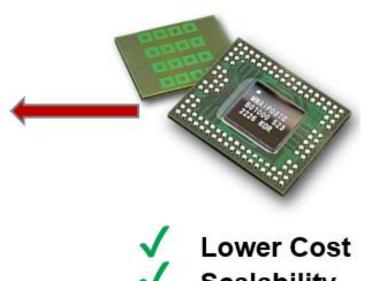




- 4x4 Antenna-in-Package
- Scalable architecture (center/corner radars)





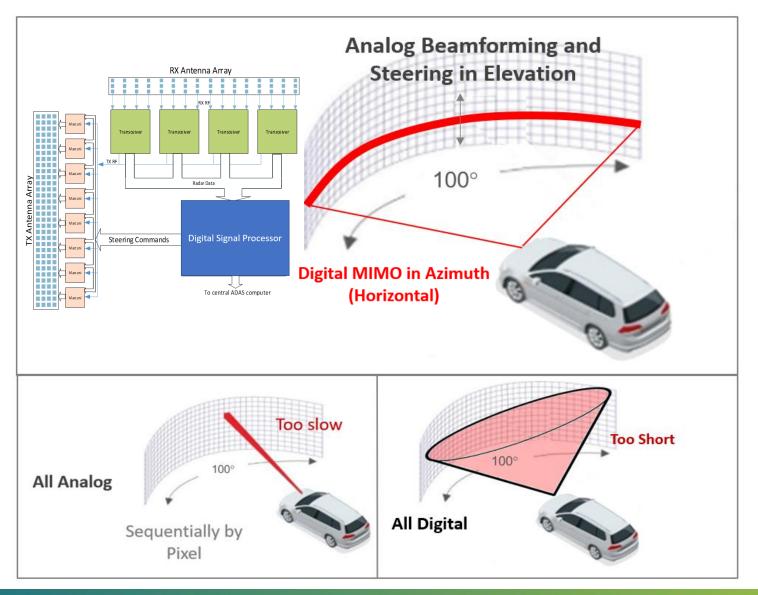






Hybrid Radar Architecture





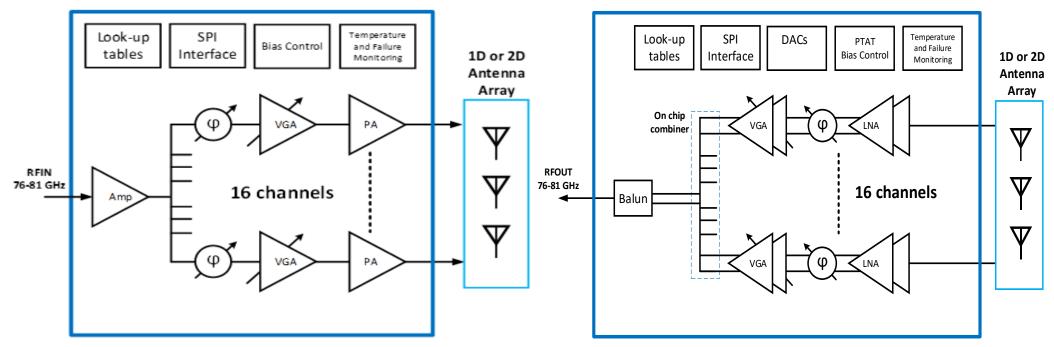
- Analog elevation beam steering
 - 32 elements in elevation for Tx beam steering in elevation
- Digital MIMO for target azimuth estimation
 - 16 RX antennas
 - 64 elements virtual array
- DDMA (Doppler Division Multiple Access)
 waveform for MIMO





Marconi TX/RF Beamformer IC





16 Channel Transmit Beamformer

16 Channel Receive Beamformer

- Die size: 5.4mm x 4.8mm (with 0.2mm-pitch C4s)
- Each frontend has PA/LNA, VGA, phase shifter, power splitter, SPI, DAC, temperature sensor, ESD protection, etc.

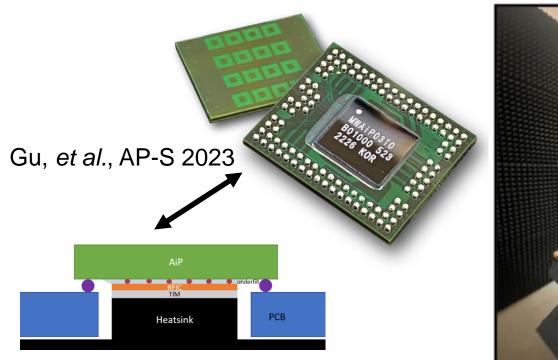


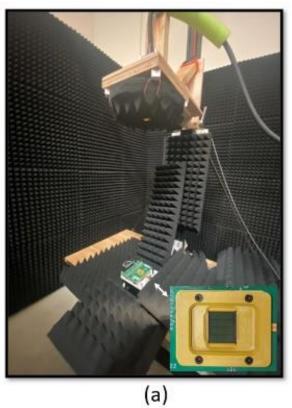


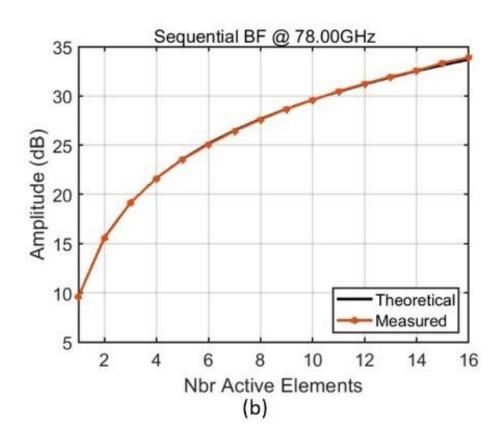


Antenna-in-Package Design and Test









- Mass-producible flip-chip AiP (12.4mm x 10.2mm x 1.1mm)
- TX module OTA calibration: excellent power combining demonstrated

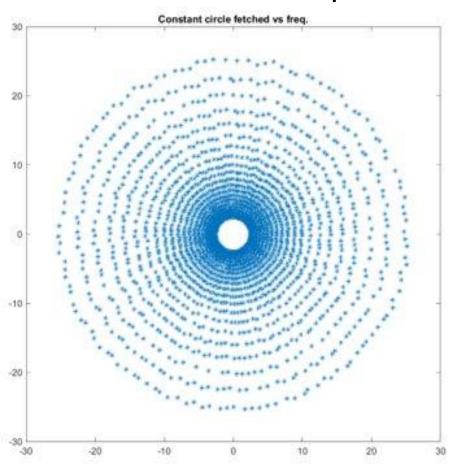


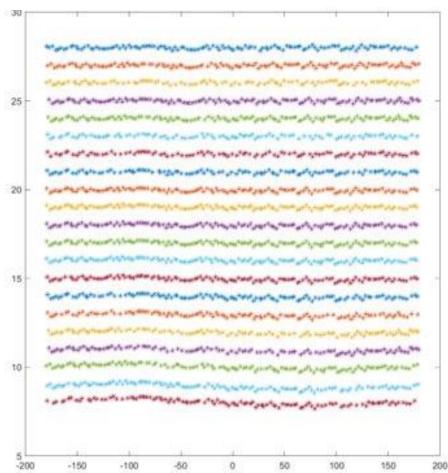


Amplitude and Phase Control Results



One representative channel at 77GHz





2.8 phase step, <0.5dB Amp step, <0.5dB variation over phase shifting



IMS Carson Imaging Radar Implementation







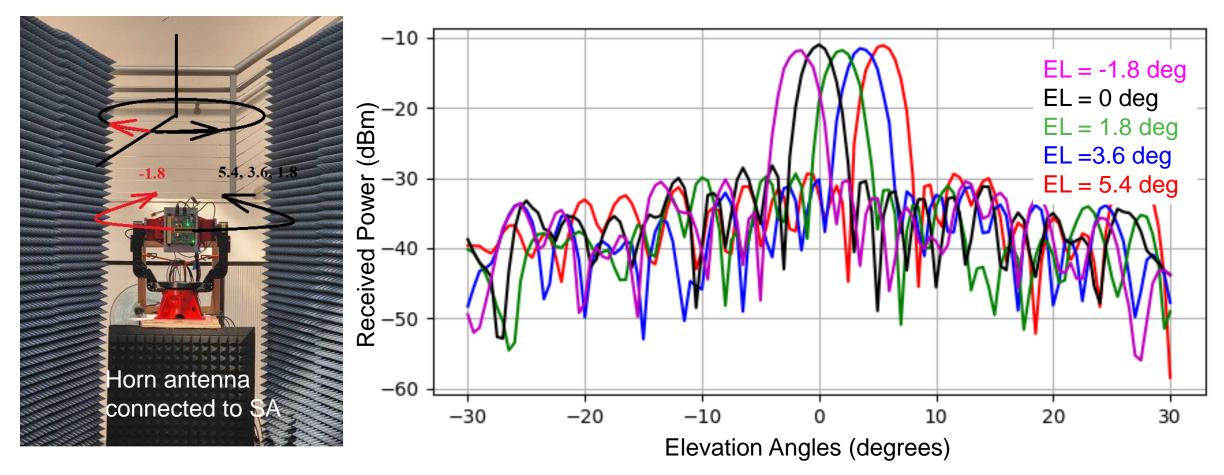
12cm x 12cm with front cover & NXP processor board

- TX Marconi AiPs (x8) + 1 Guard AiP (for testing purpose only)
- RX Antenna Array (2λ spacing)
- 4x Cascade RF TI Transceivers on the back
- NXP Processor inside Radar Unit



Connecting Minds. Exchanging Ideas. TX Elevation Beam Steering Calibration Connecting Minds. Exchanging Ideas.





- Multiple EL beams generated by an innovative calibration method
- Measured half-power beam width = 2.2 degrees

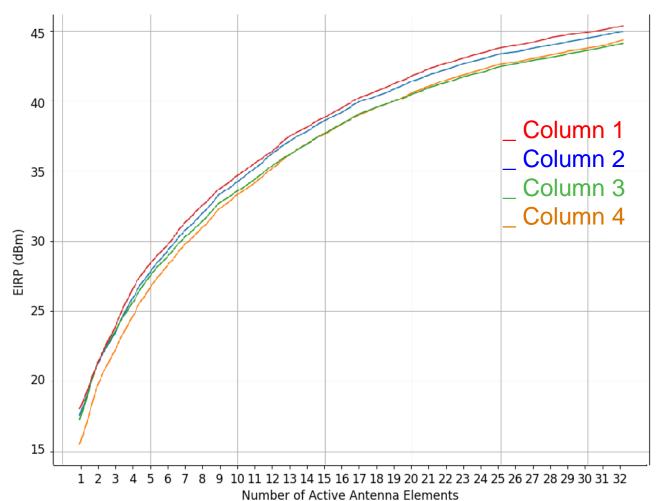






IMS TX OTA Power Combining and EIRP Measurement





- CW mode at 78 GHz
- 27dB increase for four 32element TX columns
- Measured EIRP (32-element per column): 43.5 dBm (average)
- Measured EIPR (128 elements): 53.5 dBm

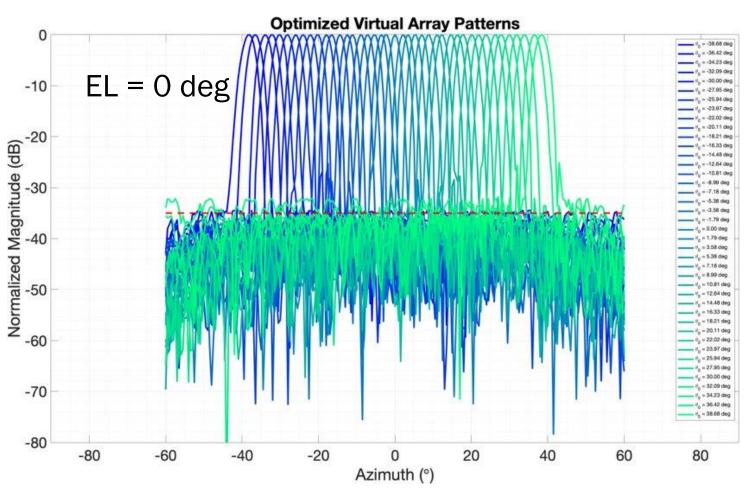




IMS Azimuth MIMO Calibration with DDMA Connecting Minds. Exchanging Ideas.







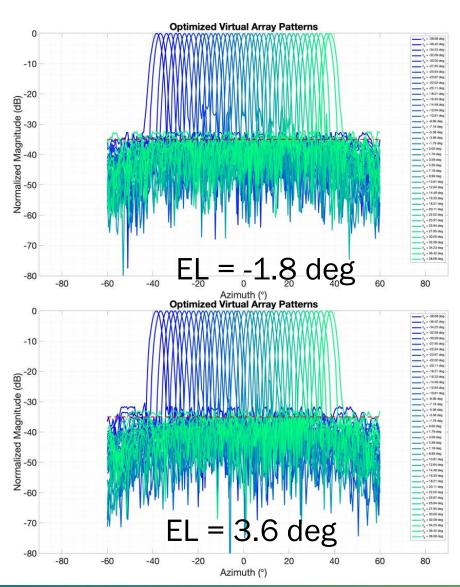
Narrow beams with ultra low (> 35dB) side-lobe levels

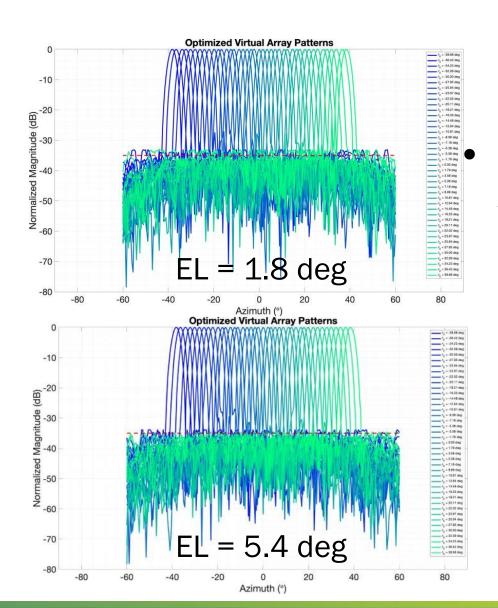




IMS Azimuth MIMO Calibration with DDMA







Excellent virtual array beam patterns in other EL directions





Carson Radar Demo Video





Road test demo video will be played during the presentation





Conclusions



- Increasing demand for automotive imaging radar.
- Digital MIMO radars have challenges for long range and in dense clutter multipath due to limitations of EIRP & SNR.
- A hybrid beam steering + MIMO imaging radar is presented:
 - Compact size and highly integrated
 - Analog steering in elevation + digital MIMO in azimuth
 - Scalable based on AiP modules
 - High EIRP & SNR
 - Excellent RF performance





Acknowledgements



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