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Practice
Paper
Finalist**

Surrogate Modeling with Complex-valued Neural Nets and its Application to Design of sub-THz Patch Antenna-in-Package

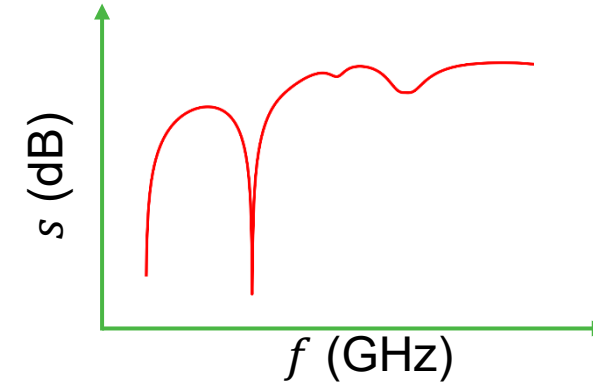
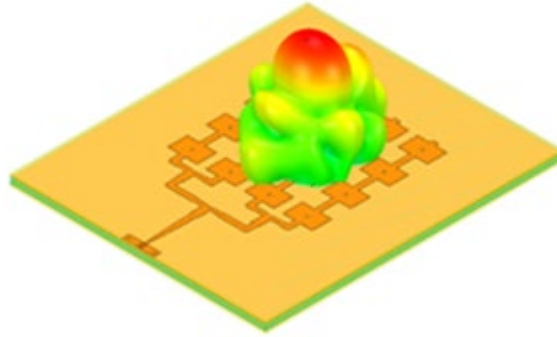
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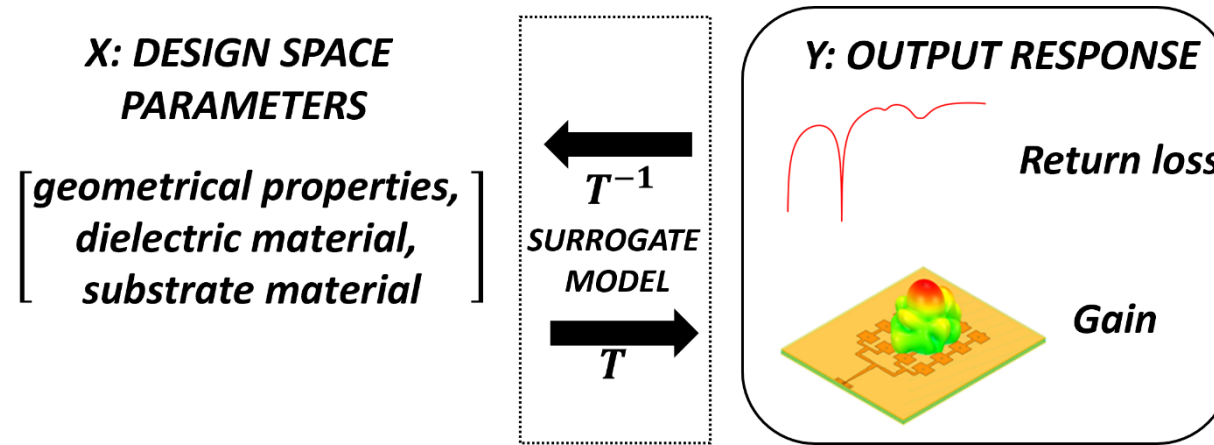


Motivation



- ❑ Simulating RF front-end modules like antennas is essential for design of wireless communications
- ❑ Simulating their behavior can be computationally and time-intensive
 - ❑ Size & complexity of the structure
 - ❑ Frequency range of interest
 - ❑ Operating environment
- ❑ Designing an antenna involves determining the suitable set of design parameters that generate the desired output response

Objectives

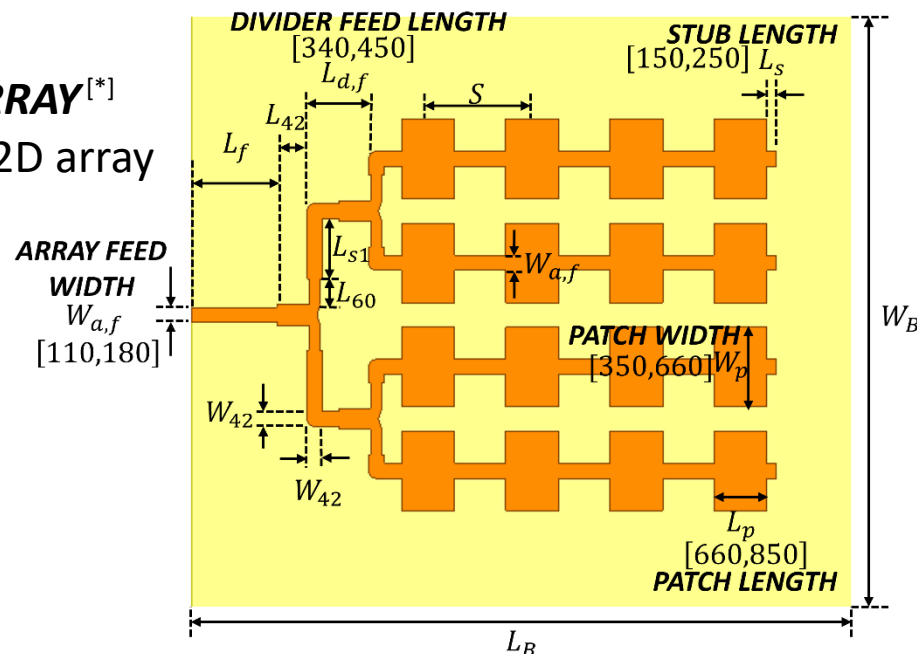


- ❑ Since Machine Learning (ML) techniques provide good representations of data
- ❑ Build a fast ML-based surrogate model that enables the designers to:
 1. Simulate their designs to meet a target spec
 2. Obtain the design parameters that correspond to a given spec

Example: Design of sub-THz Patch Array

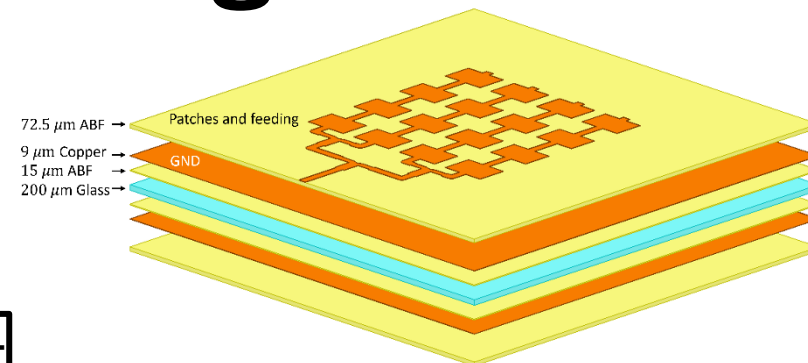
Antenna-in-package

PATCH ARRAY^[*]
□ 4 × 4 2D array



DESIGN SPACE PARAMETERS OF SUB-THz PATCH ARRAY

Parameter	Unit	Min	Max
Patch width	W_p	μm	350 660
Patch length	L_p	μm	660 850
Array Feed width	$W_{a,f}$	μm	110 180
Stub length	L_s	μm	150 250
Divider feed length	$L_{d,f}$	μm	340 450



Objectives:

→ Forward modeling

→ Inverse modeling

FREQUENCY RESPONSE
 S_{11} from [130.1, 150.05] GHz

DESIGN PARAMETERS
 $W_p, L_p, W_{a,f}, L_s, L_{d,f}$

DATA:

□ Input design space $X \in R^5$

□ Output specs $Y \in \mathbb{C}^{134}$

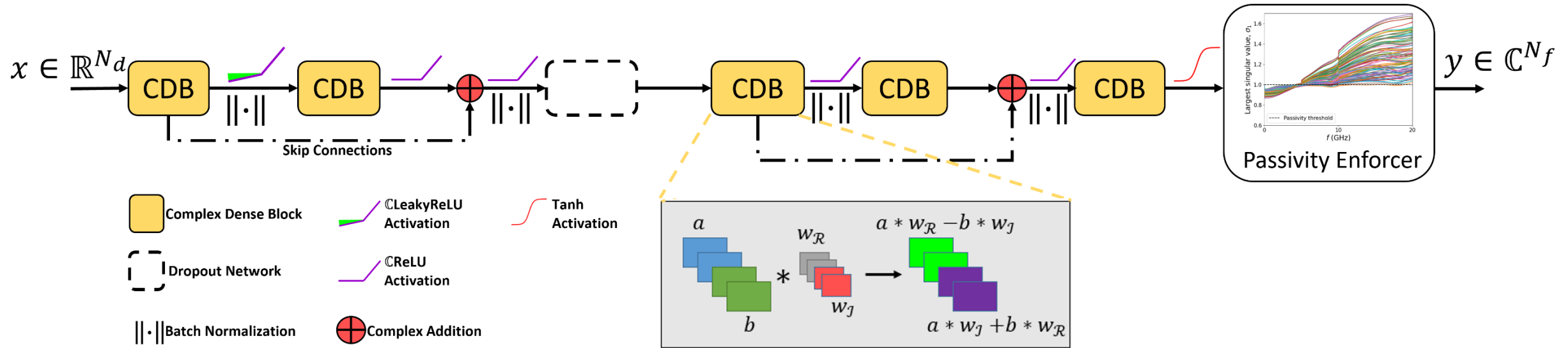
MODEL:

□ CDNet

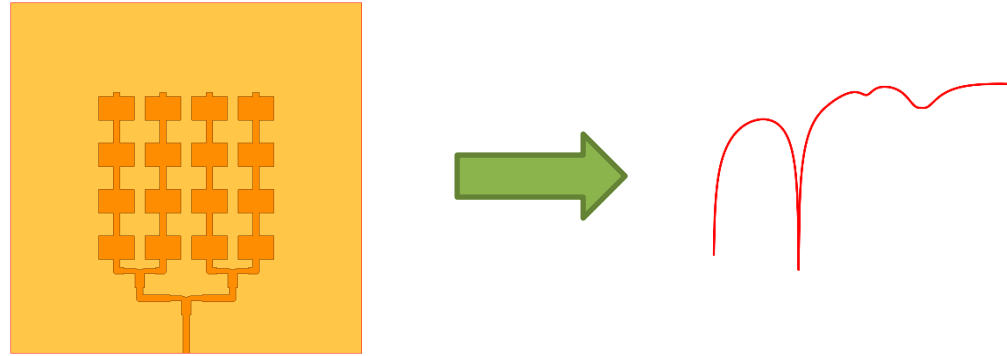
➤ 6 complex dense blocks

[*] K. -Q. Huang and M. Swaminathan, "Antennas in Glass Interposer For sub-THz Applications," (ECTC), 2021

Surrogate modeling with deep complex dense net (\mathbb{C} DNet)



Objective I: Forward modeling



- ❑ Obtain a frequency response based on given design parameters
- ❑ CDNet learns the forward mapping between the patch array design space x and the frequency response y
- ❑ Train with an ℓ_2 -supervised loss

$$\mathcal{L} = \mathbb{E}_{x,y} [\|\hat{y}_{\mathcal{R}} - y_{\mathcal{R}}\|_2^2 + \|\hat{y}_{\mathcal{I}} - y_{\mathcal{I}}\|_2^2]$$

where $\hat{y} := \text{predicted } S_{11}$, $y := \text{actual } S_{11}$

Modeling physically consistent response

Passivity of S -parameters

□ A multiport network is passive if it cannot generate energy

□ \Leftrightarrow S -parameter matrix is unitary bounded, i.e.,

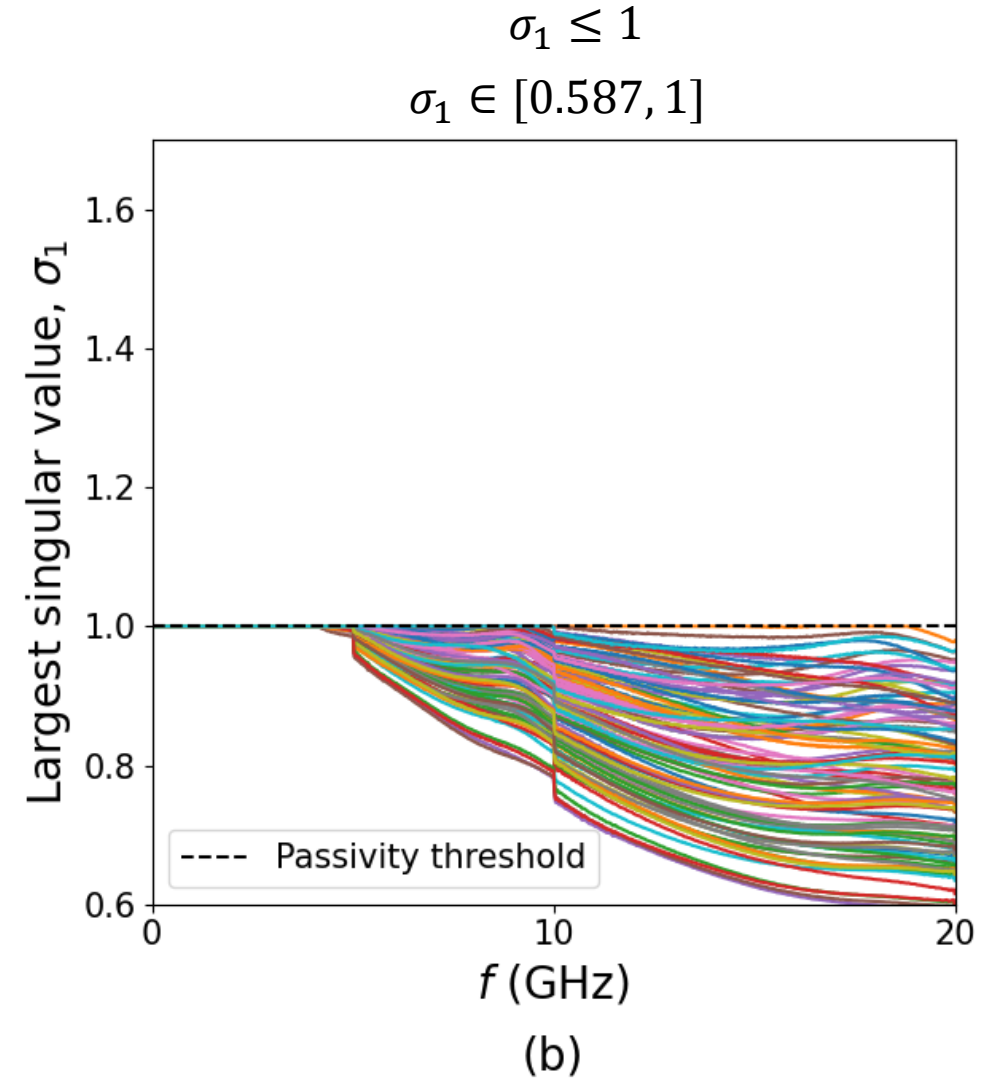
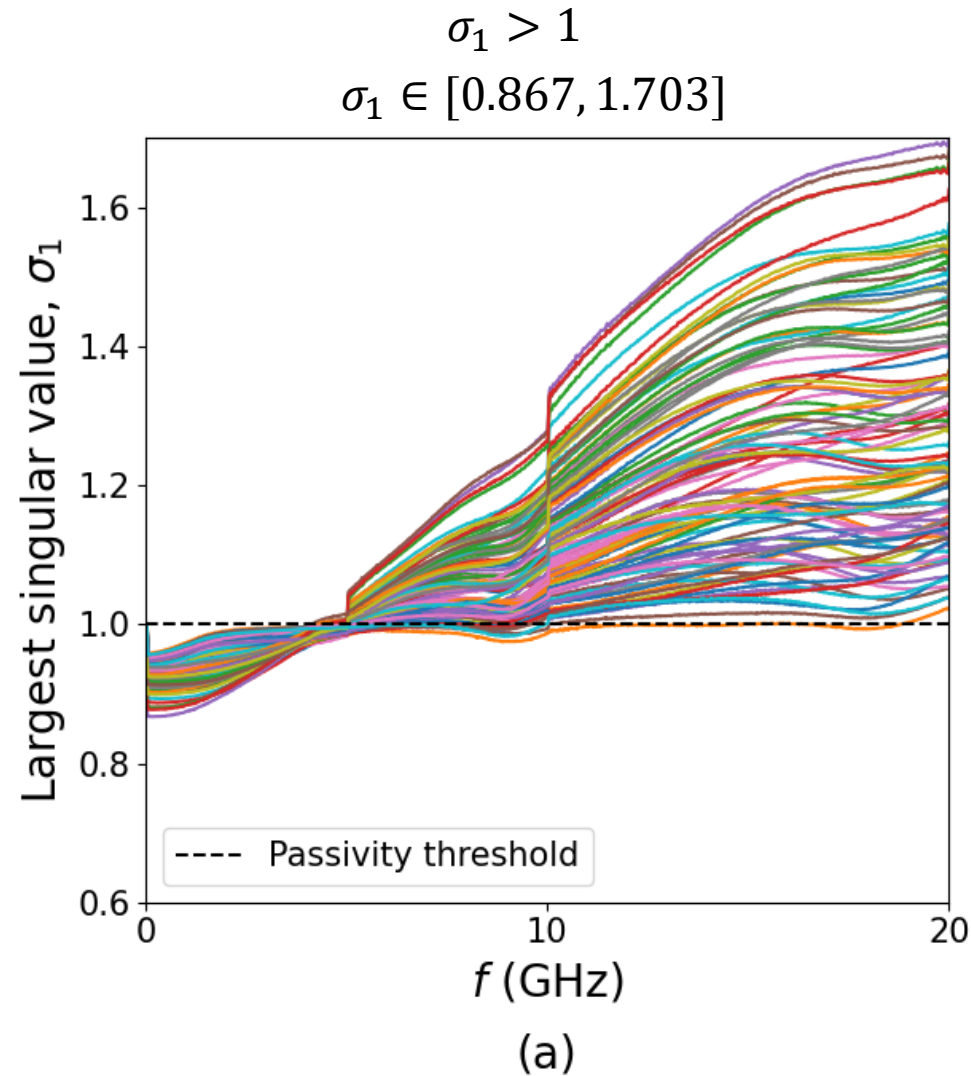
$$S^H(f)S(f) \leq I \quad \forall f \in B$$

□ $\Leftrightarrow \max_{i,f} \sigma_i(f) \leq 1, \quad i: f_i \in B$

□ All singular values must be bounded by one at all frequencies

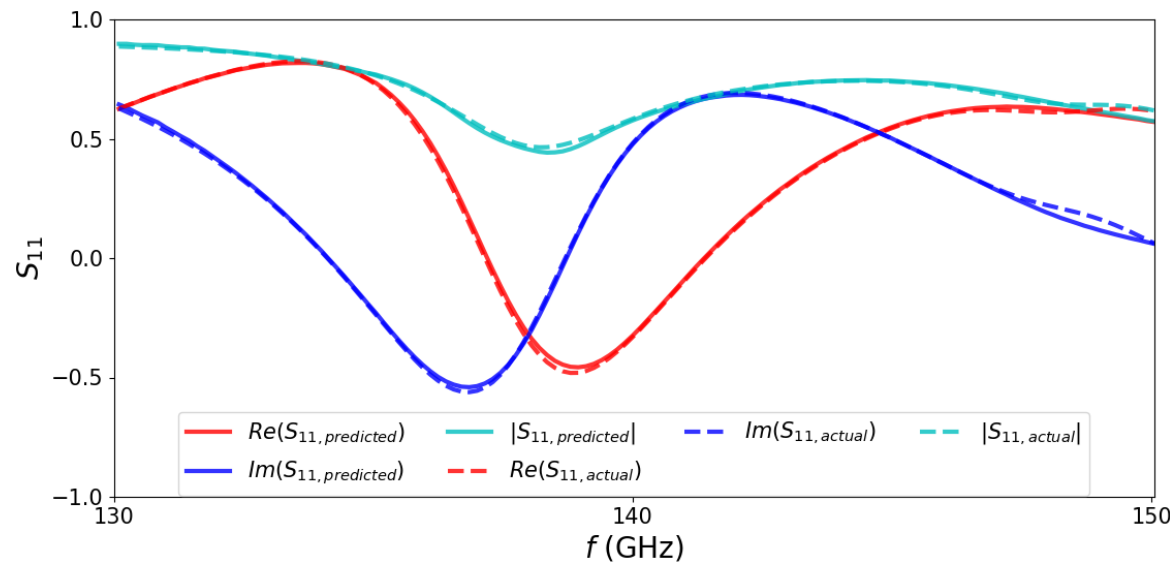
□ Passivity enforcer is added as the last layer of the NN model

Achieving physical consistency

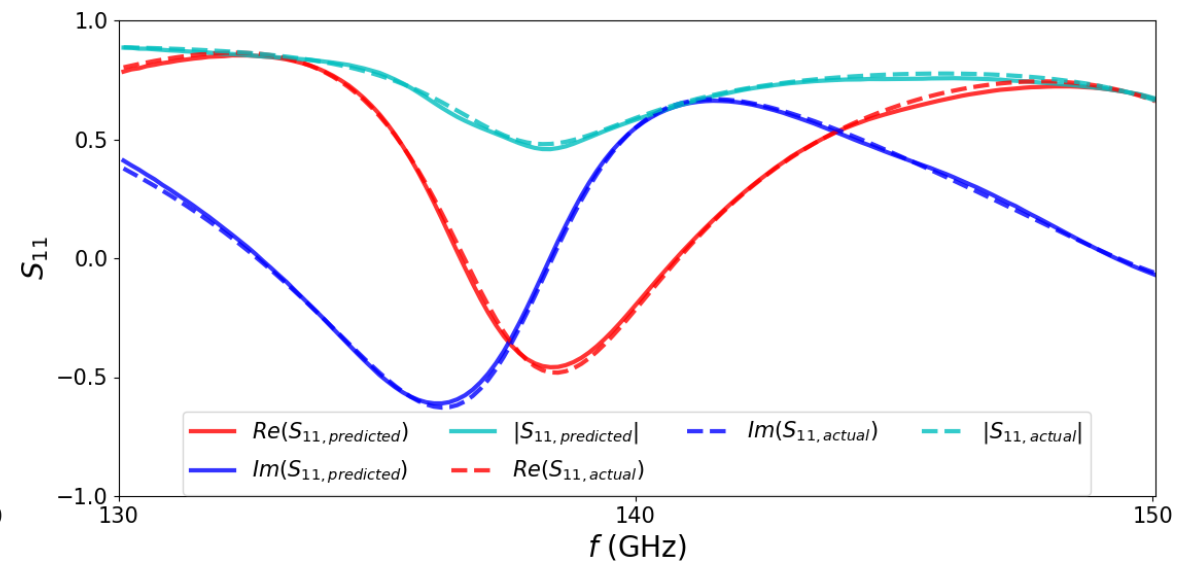


Forward modeling results

□ Perform forward inference on random samples in test set

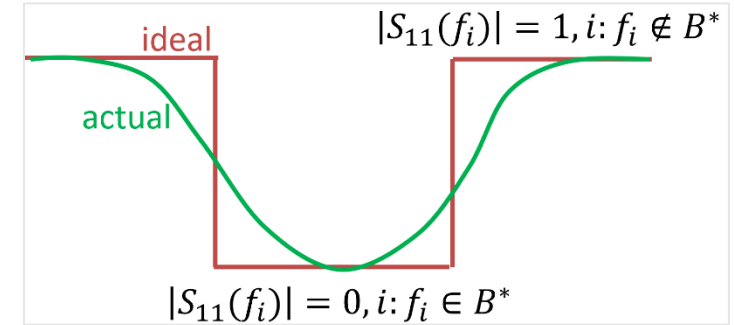
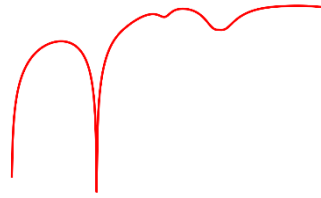
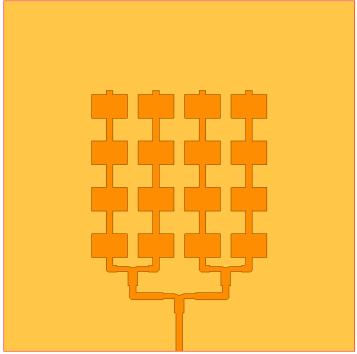


Sample A



Sample B

Objective II: Inverse optimization



- ❑ Obtain design parameters that correspond to a given spec of $|S_{11}|$
- ❑ Objective: ℓ_2 -norm of the difference between the ideal $|S_{11}|$ (i.e., y^*) and that delivered by the forward model (i.e., $\hat{y}(x)$)

$$\hat{x} = \operatorname{argmin}_x \sum_{i: f_i \in B^*} |\hat{y}_i(x)|^2 + \sum_{i: f_i \notin B^*} (|\hat{y}_i(x)| - 1)^2$$

where $\hat{x} :=$ inverse solution, $B^* :=$ target band

Objective II: Inverse optimization

Algorithm 1: Inverse optimization

Input: Initialization $x^{(0)} \in \text{dom}(g)$, trained model g with the set of all network parameters θ , target band B^* , learning rate λ

Output: estimated x

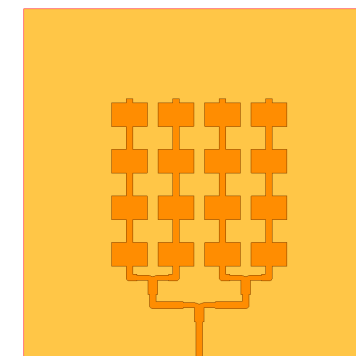
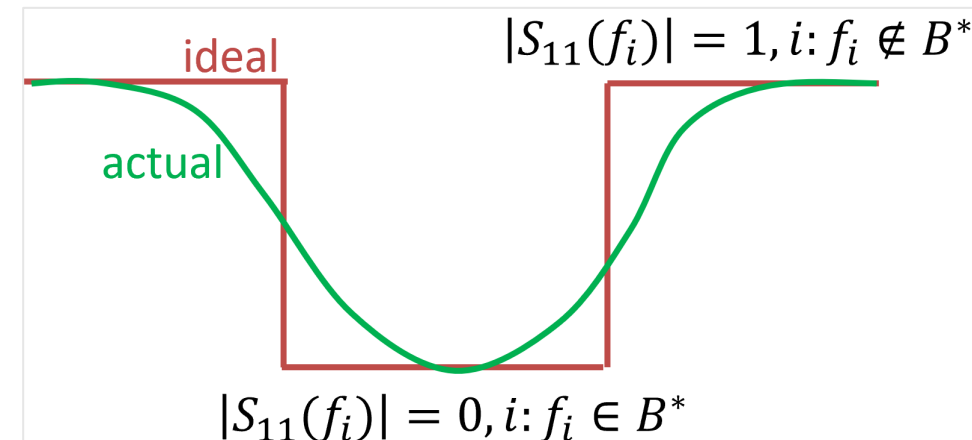
for $k = 0, 1, 2, \dots$, *until convergence*, **do**

$$\hat{y}^{(k)} = g(x^{(k)}, \theta)$$

$$\mathcal{J}(\hat{y}^{(k)}) = \sum_{i: f_i \in B^*} |\hat{y}_i^{(k)}|^2 + \sum_{i: f_i \notin B^*} (|\hat{y}_i^{(k)}| - 1)^2$$

$$\Delta x^{(k)} = - \frac{\partial \mathcal{J}(\hat{y}^{(k)})}{\partial \hat{y}^{(k)}} \frac{\partial \hat{y}^{(k)}}{\partial \theta} \frac{\partial \theta}{\partial x^{(k)}}$$

Update: $x^{(k+1)} \leftarrow x^{(k)} + \lambda \Delta x^{(k)}$



❑ Return loss passband

❑ Region where the $|S_{11}|$ is lower than -10 dB in the resonant band

$$B = \{[f_L, f_H]: |S_{11}| < -10 \text{ dB}\}$$

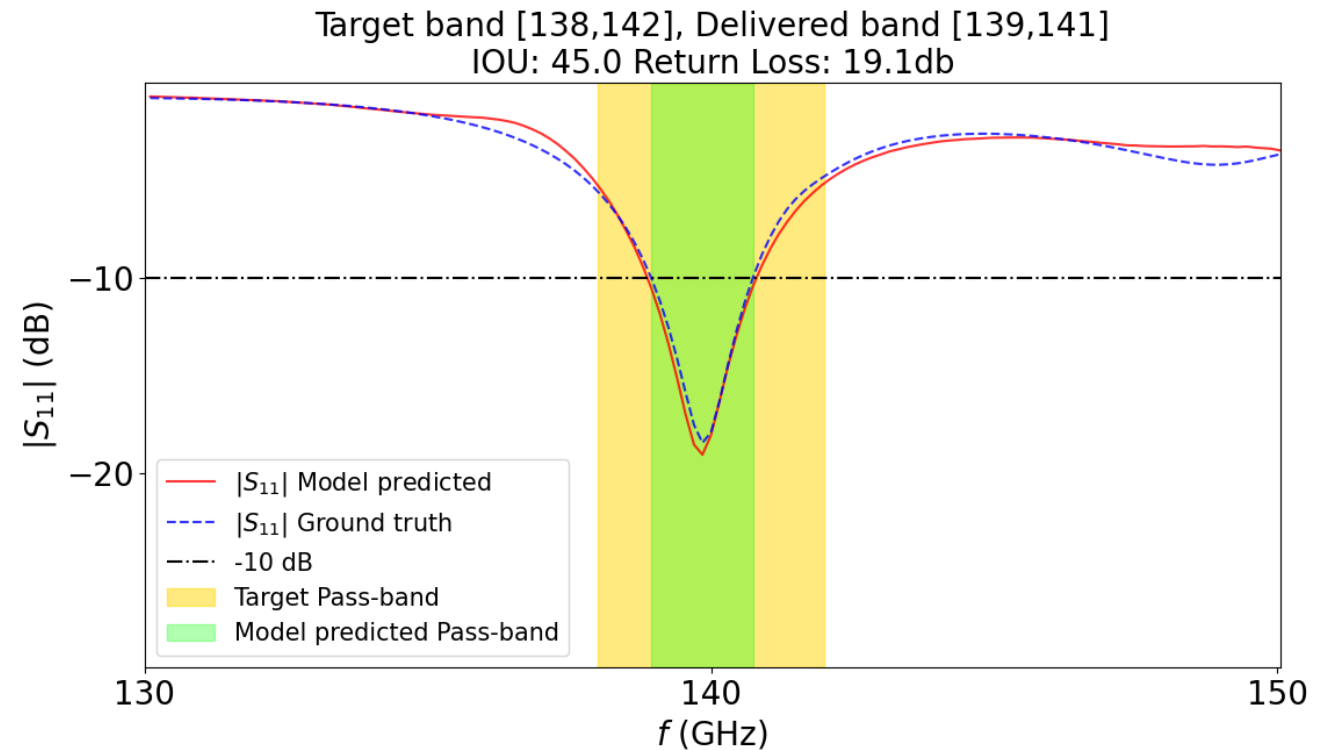
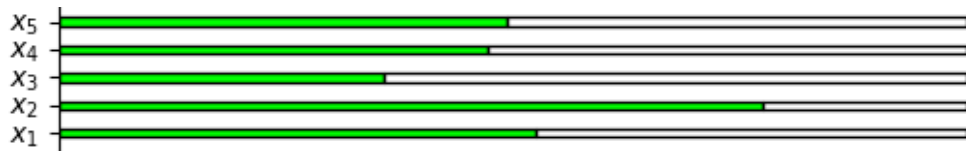
❑ Intersection-over-Union (IoU)

❑ Percentage overlap between the target band and our prediction passband

$$\text{IoU} = \frac{B^* \cap \hat{B}}{B^* \cup \hat{B}}$$

Inverse optimization results

- Given a target band $B^* = [138, 142]$ GHz
- Optimize to find the design parameters
- $\hat{x} = \{W_p, L_p, W_{a,f}, L_s, L_{d,f}\} = \{502.7, 789.8, 176.7, 210.3, 340.4\} \mu m$
- Validate with forward design



Performance Summary

- ❑ EM simulator: ~617 CPU hours to generate 2500 training data samples
- ❑ CDNet: ~2.5 seconds to inference 2500 samples
 - ❑ ~1.8 minutes to train

Table 1. Performance Summary of the Proposed Surrogate Model

Design parameters	Frequency points	Train error (for 2400 samples)	Inference error (for 100 samples)
5	134	0.641 dB	0.357 dB

$$\text{Error(dB)} = \frac{1}{N} \sum_{i=1}^N |20 \log_{10} |y_i| - 20 \log_{10} |\hat{y}_i| |$$

where y is the ground truth, and \hat{y} is the prediction

Conclusion

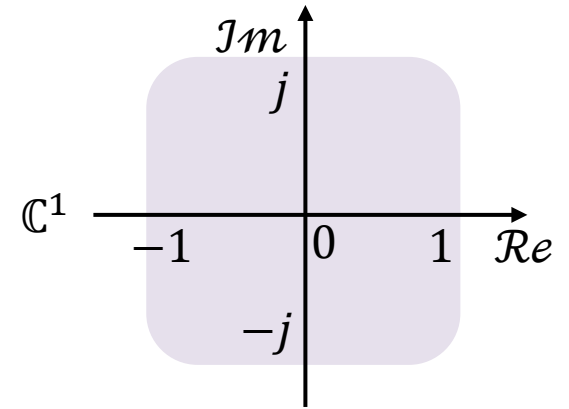
- ❑ We present both forward and inverse modeling of RF systems using complex-valued neural networks
- ❑ Forward modeling gives us a fast prototype of the circuit
- ❑ Inverse modeling involves finding the best design parameters to generate a desired response
- ❑ Surrogate modeling helps in reducing the design cycle time

THANK YOU!

This research is supported in part by
NSF I/UCRC Center for Advanced Electronics
Through Machine Learning (CAEML)

Surrogate Modeling with Complex-valued Neural Nets

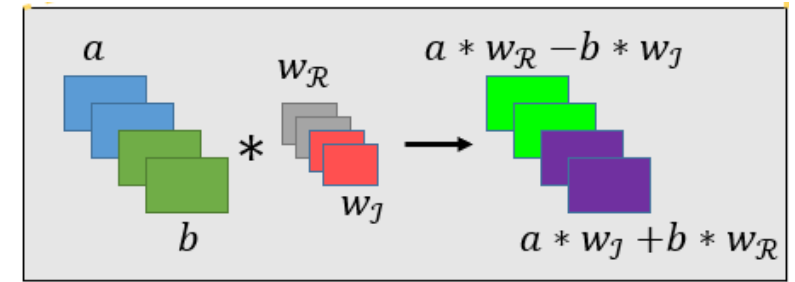
- ☐ We predominantly train NNs in the real \mathbb{R} domain
- ☐ But phase is important too!
- ☐ Complex domain \mathbb{C} offers a richer set of numbers
 - ☐ Better data representation
 - ☐ Mapping for complex-valued NNs $g(z): \mathbb{C}^N \leftrightarrow \mathbb{C}^M$
 - ☐ Mapping for real-valued NNs $h(z): \mathbb{R}^{2N} \leftrightarrow \mathbb{R}^M$
 - ☐ Higher functionality
 - ☐ Weights do not just change amplitude
 - ☐ Can be rotated too!
- ☐ Classification capability: A simple perceptron can only learn linearly separable functions
 - ☐ XOR: linearly non-separable
 - ☐ Single real-valued neuron fails
 - ☐ Single complex-valued neuron succeeds



Complex building blocks

□ Complex convolution

$$\begin{aligned} \square w *_{\mathbb{C}} z &= (a + jb) *_{\mathbb{C}} (W_J + jW_{\mathcal{R}}) \\ &= (a * W_{\mathcal{R}} - b * W_J) + j(a * W_J + b * W_{\mathcal{R}}) \end{aligned}$$



□ Complex activation

$$\square \tanh(z) = \frac{e^z - e^{-z}}{e^z + e^{-z}}$$

$$\square \mathbb{C}\text{ReLU}(z) = \text{ReLU}(a) + j\text{ReLU}(b)$$

□ Complex residual block

□ Given mapping $T(z)$ from input to output

$$\square R(z) = T(z) - z \implies T(z) = R(z) + z$$



Modeling physically consistent response:

Passivity of S -parameters

Algorithm 1: Passivity enforcement of S -parameters

Input: S : Predicted complex S -parameter matrix, n :

Number of ports, B : Frequency band

Output: S_P : Passive S -parameter matrix

1 Reshape S into a batched matrix form for an n -port network.

2 Transform S into \tilde{S} using isomorphism:

$$\tilde{S} = \begin{bmatrix} \Re(S) & \Im(S) \\ -\Im(S) & \Re(S) \end{bmatrix}$$

3 for $i : f_i \in B$ do

4 Calculate an upper bound for the largest singular value using:

$$\hat{\sigma}_1(f_i) = \sqrt{\frac{P(f_i)}{n}} + \sqrt{\frac{n-1}{n} \left(Q(f_i) - \frac{P(f_i)^2}{n} \right)}$$

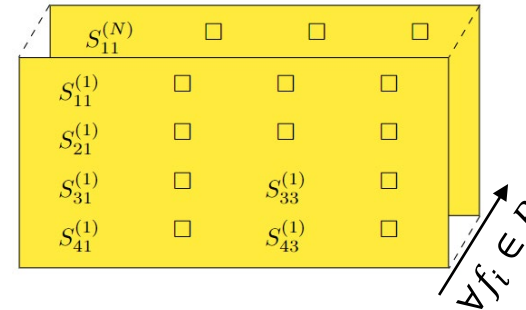
where

$$P(f_i) = \sum_{j=1}^n |\tilde{S}_{jj}(f_i)|^2 \text{ and}$$

$$Q(f_i) = \sum_{j,k=1}^n \left[\left(\tilde{S}^*(f_i) \tilde{S}(f_i) \right) \circ \left(\tilde{S}(f_i) \tilde{S}^*(f_i) \right) \right]_{jk}.$$

⋮

Step 1



5

Implement minimum-phase filter as:

$$\Sigma(f_i) = |\Sigma(f_i)| e^{j\phi(f_i)}$$

where

$$|\Sigma(f_i)| = \begin{cases} \frac{1}{\hat{\sigma}_1(f_i)}, & \text{for } \hat{\sigma}_1(f_i) > 1 \\ 1, & \text{for } \hat{\sigma}_1(f_i) \leq 1 \end{cases},$$

$$\phi(f_i) = \mathcal{H}\{\log |\Sigma(f_i)|\}.$$

/ $\mathcal{H}\{\cdot\}$ is the Hilbert transform, operated using a fast Fourier transform approach. */*

6

Enforce passivity as:

$$S_P(f_i) = \tilde{S}(f_i) \odot \Sigma(f_i).$$